



All the dimensions are in meters

## Physical and numerical side of the problem:

- In this case we are going to solve the flow around a cylinder. We are going to use incompressible and compressible solvers, in laminar and turbulent regime.
- Therefore, the governing equations of the problem are the incompressible/compressible laminar/turbulent Navier-Stokes equations.
- We are going to work in a 2D domain.
- Depending on the Reynolds number, the flow can be steady or unsteady.
- This problem has a lot of validation data.

#### Workflow of the case



## Vortex shedding behind a cylinder



Strouhal number

# Some experimental <sup>(E)</sup> and numerical <sup>(N)</sup> results of the flow past a circular cylinder at various Reynolds numbers

Reference	c <sub>d</sub> – Re = 20	L <sub>rb</sub> – Re = 20	c <sub>d</sub> – Re = 40	$L_{rb} - Re = 40$
[1] Tritton <sup>(E)</sup>	2.22	-	1.48	-
[2] Cuntanceau and Bouard <sup>(E)</sup>	_	0.73	-	1.89
[3] Russel and Wang <sup>(N)</sup>	2.13	0.94	1.60	2.29
[4] Calhoun and Wang <sup>(N)</sup>	2.19	0.91	1.62	2.18
[5] Ye et al. <sup>(N)</sup>	2.03	0.92	1.52	2.27
[6] Fornbern <sup>(N)</sup>	2.00	0.92	1.50	2.24
[7] Guerrero <sup>(N)</sup>	2.20	0.92	1.62	2.21

 $L_{rb}$  = length of recirculation bubble,  $c_d$  = drag coefficient, Re = Reynolds number,

- [1] D. Tritton. Experiments on the flow past a circular cylinder at low Reynolds numbers. Journal of Fluid Mechanics, 6:547-567, 1959.
- [2] M. Cuntanceau and R. Bouard. Experimental determination of the main features of the viscous flow in the wake of a circular cylinder in uniform translation. Part 1. Steady flow. Journal of Fluid Mechanics, 79:257-272, 1973.
- [3] D. Rusell and Z. Wang. A cartesian grid method for modeling multiple moving objects in 2D incompressible viscous flow. Journal of Computational Physics, 191:177-205, 2003.
- [4] D. Calhoun and Z. Wang. A cartesian grid method for solving the two-dimensional streamfunction-vorticity equations in irregular regions. Journal of Computational Physics. 176:231-275, 2002.
- [5] T. Ye, R. Mittal, H. Udaykumar, and W. Shyy. An accurate cartesian grid method for viscous incompressible flows with complex immersed boundaries. Journal of Computational Physics, 156:209-240, 1999.
- [6] B. Fornberg. A numerical study of steady viscous flow past a circular cylinder. Journal of Fluid Mechanics, 98:819-855, 1980.
- [7] J. Guerrero. Numerical simulation of the unsteady aerodynamics of flapping flight. PhD Thesis, University of Genoa, 2009.

# Some experimental <sup>(E)</sup> and numerical <sup>(N)</sup> results of the flow past a circular cylinder at various Reynolds numbers

Reference	c <sub>d</sub> – Re = 100	c <sub>1</sub> – Re = 100	c <sub>d</sub> – Re = 200	c <sub>I</sub> – Re = 200
[1] Russel and Wang <sup>(N)</sup>	$1.38\pm0.007$	± 0.322	$1.29\pm0.022$	± 0.50
[2] Calhoun and Wang <sup>(N)</sup>	$1.35\pm0.014$	$\pm 0.30$	$\textbf{1.17} \pm \textbf{0.058}$	± 0.67
[3] Braza et al. <sup>(N)</sup>	$1.386 \pm 0.015$	± 0.25	$1.40\pm0.05$	± 0.75
[4] Choi et al. <sup>(N)</sup>	$1.34\pm0.011$	± 0.315	$1.36\pm0.048$	± 0.64
[5] Liu et al. <sup>(N)</sup>	$1.35\pm0.012$	± 0.339	$1.31\pm0.049$	± 0.69
[6] Guerrero <sup>(N)</sup>	$1.38\pm0.012$	± 0.333	$1.408\pm0.048$	± 0.725

 $c_{l}$  = lift coefficient,  $c_{d}$  = drag coefficient, Re = Reynolds number

[1] D. Rusell and Z. Wang. A cartesian grid method for modeling multiple moving objects in 2D incompressible viscous flow. Journal of Computational Physics, 191:177-205, 2003.

[2] D. Calhoun and Z. Wang. A cartesian grid method for solving the two-dimensional streamfunction-vorticity equations in irregular regions. Journal of Computational Physics. 176:231-275, 2002.
 [3] M. Braza, P. Chassaing, and H. Hinh. Numerical study and physical analysis of the pressure and velocity fields in the near wake of a circular cylinder. Journal of Fluid Mechanics, 165:79-130, 1986.

[4] J. Choi, R. Oberoi, J. Edwards, an J. Rosati. An immersed boundary method for complex incompressible flows. Journal of Computational Physics, 224:757-784, 2007.

[5] C. Liu, X. Zheng, and C. Sung. Preconditioned multigrid methods for unsteady incompressible flows. Journal of Computational Physics, 139:33-57, 1998.

[6] J. Guerrero. Numerical Simulation of the unsteady aerodynamics of flapping flight. PhD Thesis, University of Genoa, 2009.

At the end of the day, you should get something like this



Instantaneous velocity magnitude field www.wolfdynamics.com/wiki/cylinder\_vortex\_shedding/movvmag.gif Instantaneous vorticity magnitude field www.wolfdynamics.com/wiki/cylinder vortex shedding/movvort.gif

Incompressible flow – Reynolds 200

At the end of the day, you should get something like this



Incompressible flow – Reynolds 200

• Let us run this case. Go to the directory:

## \$PTOFC/vortex\_shedding

- \$PTOFC is pointing to the directory where you extracted the training material.
- In the case directory, you will find the README.FIRST file. In this file, you will find the general instructions of how to run the case. In this file, you might also find some additional comments.
- You will also find a few additional files (or scripts) with the extension .sh, namely, run\_all.sh, run\_mesh.sh, run\_sampling.sh, run\_solver.sh, and so on. These files can be used to run the case automatically by typing in the terminal, for example, sh run\_solver.
- We highly recommend you to open the README.FIRST file and type the commands in the terminal, in this way, you will get used with the command line interface and OpenFOAM® commands.
- If you are already comfortable with OpenFOAM®, use the automatic scripts to run the cases.

#### What are we going to do?

- We will use this case to learn how to use different solvers and utilities.
- Remember, different solvers have different input dictionaries.
- We will learn how to convert the mesh from a third party software.
- We will learn how to use setFields to accelerate the convergence.
- We will learn how to map a solution from a coarse mesh to a fine mesh.
- We will learn how to setup a compressible solver.
- We will learn how to setup a turbulence case.
- We will use gnuplot to plot and compute the mean values of the lift and drag coefficients.
- We will visualize unsteady data.

### Running the case

- Let us first convert the mesh from a third-party format (Fluent format).
- You will find this tutorial in the directory **\$PTOFC/1010F/vortex\_shedding/c2**
- In the terminal window type:

```
    $> foamCleanTutorials
    $> fluent3DMeshToFoam ../../meshes_and_geometries/vortex_shedding/ascii.msh
    $> checkMesh
    $> paraFoam
```

- In step 2, we convert the mesh from Fluent format to OpenFOAM® format. Have in mind that the Fluent mesh must be in ascii format.
- If we try to open the mesh using paraFoam (step 4), it will crash. Can you tell what is the problem (read the screen)?

#### Running the case

• To avoid this problem, type in the terminal,

```
1. $> paraFoam -builtin
```

 Basically, the problem is related to the names and type of the patches in the file boundary and the boundary conditions (U, p). Notice that OpenFOAM® is telling you what and where is the error.

Created temporary 'c2.OpenFOAM'
> FOAM FATAL IO ERROR:
patch type 'patch' not constraint type 'empty' <b>What</b> What Where for patch front of field p in file "/home/joegi/my_cases_course/5x/1010F/vortex_shedding/c2/0/p"
file: /home/joegi/my_cases_course/5x/1010F/vortex_shedding/c2/0/p.boundaryField.front from line 60 to line 60.
From function Foam::emptyFvPatchField <type>::emptyFvPatchField(const Foam::fvPatch&amp;, const Foam::DimensionedField<type, foam::volmesh="">&amp;, const Foam::dictionary&amp;) [with Type = double] in file fields/fvPatchFields/constraint/empty/emptyFvPatchField.C at line 80.</type,></type>
FOAM exiting

- Remember, when converting meshes the **name** and **type** of the patches are not always set as you would like, so it is always a good idea to take a look at the file *boundary* and modify it according to your needs.
- Let us modify the *boundary* dictionary file.
- In this case, we would like to setup the following **numerical type** boundary conditions.



Ê

The boundary dictionary file

18	7		
19	(		
20		out	
21		{	
22		type	patch;
23		nFaces	80;
24		startFace	18180;
25		}	
26		sym1	
27		{	
28		type	symmetry;
29		inGroups	1 (symmetry) ;
30		nFaces	100;
31		startFace	18260;
32		}	
33		sym2	
34		{	
35		type	symmetry;
36		inGroups	1(symmetry);
37		nFaces	100;
38		startFace	18360;
39		}	
40		in	
41		{	
42		type	patch;
43		nFaces	80;
44		startFace	18460;
45		}	

- This dictionary is located in the constant/polyMesh directory.
- This file is automatically created when converting or generating the mesh.
- To get a visual reference of the patches, you can the mesh with paraFoam/paraview.
- The type of the **out** patch is OK.
- The type of the **sym1** patch is OK.
- The type of the **sym2** patch is OK.
- The type of the **in** patch is OK.

### The boundary dictionary file



|≡]

- The type of the **cylinder** patch is OK.
- The type of the **back** patch is **NOT OK**. Remember, this is a 2D simulation, therefore the type should be **empty**.
- The type of the **front** patch is **NOT OK**. Remember, this is a 2D simulation, therefore the type should be **empty**.
- Remember, we assign the **numerical type** boundary conditions (numerical values), in the field files found in the directory *0*

- At this point, check that the name and type of the base type boundary conditions and numerical type boundary conditions are consistent. If everything is ok, we are ready to go.
- Do not forget to explore the rest of the dictionary files, namely:
  - 0/p (p is defined as relative pressure)
  - 0/U
  - constant/transportProperties
  - system/controlDict
  - system/fvSchemes
  - system/fvSolution
- Reminder:
  - The diameter of the cylinder is 2.0 m.
  - And we are targeting for a Re = 200.

$$\nu = \frac{\mu}{\rho}$$
  $Re = \frac{\rho \times U \times D}{\mu} = \frac{U \times D}{\nu}$ 

### Running the case

- You will find this tutorial in the directory **\$PTOFC/1010F/vortex\_shedding/c2**
- In the folder c1 you will find the same setup, but to generate the mesh we use blockMesh (the mesh is identical).
- To run this case, in the terminal window type:

```
    $> renumberMesh -overwrite
    $> icoFoam | tee log.icofoam
    $> pyFoamPlotWatcher.py log.icofoam
    $> pyFoamPlotWatcher.py log.icofoam
    You will need to launch this script in a different terminal
    $> gnuplot scripts0/plot_coeffs
    You will need to launch this script in a different terminal
    $> paraFoam
```

#### Running the case

- In step 1 we use the utility renumberMesh to make the linear system more diagonal dominant, this will speed-up the linear solvers. This is inexpensive (even for large meshes), therefore is highly recommended to always do it.
- In step 2 we run the simulation and save the log file. Notice that we are sending the job to background.
- In step 3 we use pyFoamPlotWatcher.py to plot the residuals on-the-fly. As the job is running in background, we can launch this utility in the same terminal tab.
- In step 4 we use the gnuplot script scripts0/plot\_coeffs to plot the force coefficients on-the-fly. Besides monitoring the residuals, is always a good idea to monitor a quantity of interest. Feel free to take a look at the script and to reuse it.
- The force coefficients are computed using functionObjects.
- After the simulation is over, we use paraFoam to visualize the results. Remember to use the VCR Controls to animate the solution.
- In the folder c1 you will find the same setup, but to generate the mesh we use blockMesh (the mesh is identical).

- At this point try to use the following utilities. In the terminal type:
  - \$> postProcess -func vorticity -noZero
     This utility will compute and write the vorticity field. The -noZero option means do not compute the vorticity field for the solution in the directory 0. If you do not add the -noZero option, it will compute and write the vorticity field for all the saved solutions, including 0
  - \$> postprocess -func 'grad(U)' -latestTime
     This utility will compute and write the velocity gradient or grad(U) in the whole domain (including at the walls). The -latestTime option means compute the velocity gradient only for the last saved solution.
  - \$> postprocess -func 'grad(p)'

This utility will compute and write the pressure gradient or grad (U) in the whole domain (including at the walls).

• \$> postProcess -func 'div(U)'

This utility will compute and write the divergence of the velocity field or grad(U) in the whole domain (including at the walls). You will need to add the keyword **div(U) Gauss linear**; in the dictionary fvSchemes.

• \$> foamToVTK -time 50:300

This utility will convert the saved solution from OpenFOAM® format to VTK format. The -time 50:300 option means convert the solution to VTK format only for the time directories 50 to 300

• \$> pisoFoam -postProcess -func CourantNo

This utility will compute and write the Courant number. This utility needs to access the solver database for the physical properties and additional quantities, therefore we need to tell what solver we are using. As the solver icoFoam does not accept the option -postProcess, we can use the solver pisoFoam instead. Remember, icoFoam is a fully laminar solver and pisoFoam is a laminar/turbulent solver.

• \$> pisoFoam -postProcess -func wallShearStress

This utility will compute and write the wall shear stresses at the walls. As no arguments are given, it will save the wall shear stresses for all time steps.

#### Non-uniform field initialization

- In the previous case, it took about 150 seconds of simulation ime to onset the instability.
- If you are not interested in the initial transient or if you want to speed-up the computation, you can add a perturbation in order to trigger the onset of the instability.
- Let us use the utility setFields to initialize a non-uniform flow.
- This case is already setup in the directory

\$PTOFC/1010F/vortex\_shedding/c3

• Let us run the same case but using a non-uniform field



#### The setFieldsDict dictionary

٠



- This dictionary file is located in the directory **system**.
- In lines 17-20 we set the default value of the velocity vector to be (0 0 0) in the whole domain.
- In lines 24-31, we initialize a rectangular region (box) just behind the cylinder with a velocity vector equal to (0.98480 0.17364 0)
  - In this case, setFields will look for the dictionary file U and it will overwrite the original values according to the regions defined in setFieldsDict.



- Let us run the same case but using a non-uniform field.
- You will find this tutorial in the directory \$PTOFC/1010F/vortex\_shedding/c3
- Feel free to use the Fluent mesh or the mesh generated with blockMesh. Hereafter, we will use blockMesh.
- To run this case, in the terminal window type:

```
$> foamCleanTutorials
1.
2.
     $> blockMesh
    $> rm -rf 0 > /dev/null 2>&1
3.
     $> cp -r 0 org/ 0
4.
     $> setFields
5.
     $> renumberMesh -overwrite
6.
     $> icoFoam | log.icofoam
7.
     $> pyFoamPlotWatcher.py log.icofoam
8.
     You will need to launch this script in a different terminal
     $> gnuplot scripts0/plot coeffs
9.
     You will need to launch this script in a different terminal
10.
        paraFoam
```

#### Running the case – Non-uniform field initialization

- In step 2 we generate the mesh using blockMesh. The name and type of the patches are already set in the dictionary blockMeshDict so there is no need to modify the boundary file.
- In step 4 we copy the original files to the directory 0. We do this to keep a backup of the original files as the file *O/U* will be overwritten when using setFields.
- In step 5 we initialize the solution using setFields.
- In step 6 we use the utility renumberMesh to make the linear system more diagonal dominant, this will speed-up the linear solvers.
- In step 7 we run the simulation and save the log file. Notice that we are sending the job to background.
- In step 8 we use pyFoamPlotWatcher.py to plot the residuals on-the-fly. As the job is running in background, we can launch this utility in the same terminal tab.
- In step 9 we use the gnuplot script scripts0/plot\_coeffs to plot the lift and drag coefficients on-the-fly. Besides monitoring the residuals, is always a good idea to monitor a quantity of interest. Feel free to take a look at the script and to reuse it.

#### Does non-uniform field initialization make a difference?

- A picture is worth a thousand words. No need to tell you yes, even if the solutions are slightly different.
- This bring us to the next subject, for how long should we run the simulation?





#### For how long should run the simulation?



- This is the difficult part when dealing with unsteady flows.
- Usually you run the simulation until the behavior of a quantity of interest does not oscillates or it becomes periodic.
- In this case we can say that after the 50 seconds mark the solution becomes periodic, therefore there is no need to run up to 350 seconds (unless you want to gather a lot of statistics).
- We can stop the simulation at 150 seconds (or maybe less), and do the average of the quantities between 100 and 150 seconds.

#### What about the residuals?



- Residuals are telling you a lot, but they are difficult to interpret.
- In this case the fact that the initial residuals are increasing after about 10 seconds, does not mean that the solution is diverging. This is in indication that something is happening (in this case the onset of the instability).
- Remember, the residuals should always drop to the tolerance criteria set in the fvSolution dictionary (final residuals). If they do not drop to the desired tolerance, we are talking about unconverged time-steps.
- Things that are not clear from the residuals:
  - For how long should we run the simulation?
  - Is the solution converging to the right value?

#### How to compute force coefficients

```
68
       functions
69
       ſ
195
           forceCoeffs object
196
           £
205
                type forceCoeffs;
206
                functionObjectLibs ("libforces.so");
208
               patches (cylinder);
209
210
               pName p;
211
                Uname U;
212
                rhoName rhoInf;
213
                rhoInf 1.0;
214
215
               //// Dump to file
216
                log true;
217
218
                CofR (0.0 0 0);
219
                liftDir (0 1 0);
220
                dragDir (1 \ 0 \ 0);
221
               pitchAxis (0 0 1);
222
               magUInf 1.0;
223
               lRef 1.0;
224
               Aref 2.0;
225
226
               outputControl
                                timeStep;
227
               outputInterval 1;
228
           }
255
       };
```

- To compute the force coefficients we use **functionObjects**.
- Remember, functionObjects are defined at the end of the *controlDict* dictionary file.
- In line 195 we give a name to the functionObject.
- In line 208 we define the patch where we want to compute the forces.
- In lines 212-213 we define the reference density value.
- In line 218 we define the center of rotation (for moments).
- In line 219 we define the lift force axis.
- In line 220 we define the drag force axis.
- In line 221 we define the axis of rotation for moment computation.
- In line 223 we give the reference length (for computing the moments)
- In line 224 we give the reference area (in this case the frontal area).
- The output of this functionObject is saved in the file forceCoeffs.dat located in the directory forceCoeffs\_object/0/

#### Can we compute basic statistics of the force coefficients using gnuplot?

- Yes we can. Enter the gnuplot prompt and type:
  - 1. gnuplot> stats 'postProcessing/forceCoeffs\_object/0/forceCoeffs.dat' u 3 This will compute the basic statistics of all the rows in the file forceCoeffs.dat (we are sampling column 3 in the input file)
  - 2. gnuplot> stats 'postProcessing/forceCoeffs\_object/0/forceCoeffs.dat' every ::3000::7000 u 3 This will compute the basic statistics of rows 3000 to 7000 in the file forceCoeffs.dat (we are sampling column 3 in the input file)
  - 3. gnuplot> plot `postProcessing/forceCoeffs\_object/0/forceCoeffs.dat' u 3 w l This will plot column 3 against the row number (iteration number)
  - 4. gnuplot> exit To exit gnuplot

• Remember the force coefficients information is saved in the file <code>forceCoeffs.dat</code> located in the directory <code>postProcessing/forceCoeffs\_object/0</code>

#### On the solution accuracy



- At the end of the day we want a solution that is second order accurate.
- We define the discretization schemes (and therefore the accuracy) in the dictionary *fvSchemes*.
- In this case, for time discretization (**ddtSchemes**) we are using the **backward** method.
- For gradient discretization (gradSchemes) we are using the leastSquares method with slope limiters (cellLimited).
- For the discretization of the convective terms (divSchemes) we are using linearUpwindV interpolation method for the term div(rho,U).
- For the discretization of the Laplacian (laplacianSchemes and snGradSchemes) we are using the Gauss linear limited 1 method
- This method is second order accurate.

#### On the solution tolerance and linear solvers

```
17
      solvers
18
      ſ
31
          р
32
          ł
33
               solver
                                 GAMG ;
34
               tolerance
                                 1e-6;
35
               relTol
                                 0;
36
                                 GaussSeidel;
               smoother
37
               nPreSweeps
                                 0;
38
               nPostSweeps
                                 2;
39
               cacheAgglomeration on;
40
               agglomerator
                                 faceAreaPair;
41
               nCellsInCoarsestLevel 100;
42
               mergeLevels
                                 1;
43
          }
44
45
          pFinal
46
          £
47
               $p;
48
               relTol
                                0;
49
          }
50
51
          υ
52
          £
53
               solver
                                PBiCG;
54
               preconditioner
                               DILU;
55
               tolerance
                                1e - 08;
56
               relTol
                                0;
57
          }
69
      }
70
71
      PISO
72
      {
73
          nCorrectors
                           2:
74
          nNonOrthogonalCorrectors 2;
77
      }
```

- We define the solution tolerance and linear solvers in the dictionary *fvSolution*.
- To solve the pressure (**p**) we are using the **GAMG** method with an absolute **tolerance** of 1e-6 and a relative tolerance **reITol** of 0.01.
- The entry **pFinal** refers to the final correction of the **PISO** loop. It is possible to use a tighter convergence criteria only in the last iteration.
- To solve **U** we are using the solver **PBiCG** and the **DILU** preconditioner, with an absolute **tolerance** of 1e-8 and a relative tolerance **reITol** of 0 (the solver will stop iterating when it meets any of the conditions).
- Solving for the velocity is relative inexpensive, whereas solving for the pressure is expensive.
- The PISO sub-dictionary contains entries related to the pressure-velocity coupling (in this case the PISO method). Hereafter we are doing two PISO correctors (nCorrectors) and two non-orthogonal corrections (nNonOrthogonalCorrectors).

#### On the runtime parameters

17	application	icoFoam;
18		
20	startFrom	<pre>latestTime;</pre>
21		
22	startTime	0;
23		
24	stopAt	endTime;
26		
27	endTime	350;
29		
33	deltaT	0.05;
34		
35	writeControl	runTime;
43		
44	writeInterval	1;
45		
52	purgeWrite	0;
53		
54	writeFormat	ascil;
55		
56	WritePrecision	8;
57		
58	writecompressio	n oll;
59	timeTermet	
60	LIMerormat	general;
60	timeDreaiaian	6.
62	LIMEPrecision	<b>o</b> ;
64	mun <b>∏imoModifi</b> ah	
04	Tuilliemouilac	te true;

- This case starts from the latest saved solution (startFrom).
- In this case as there are no saved solutions, it will start from 0 (startTime).
- It will run up to 350 seconds (endTime).
- The time step of the simulation is 0.05 seconds (**deltaT**). The time step has been chosen in such a way that the Courant number is less than 1
- It will write the solution every 1 second (**writeInterval**) of simulation time (**runTime**).
- It will keep all the solution directories (purgeWrite).
- It will save the solution in ascii format (writeFormat).
- The write precision is 8 digits (writePrecision).
- And as the option **runTimeModifiable** is on, we can modify all these entries while we are running the simulation.

#### The output screen



#### Let us use a potential solver to find a quick solution

- In this case we are going to use the potential solver potentialFoam (remember potential solvers are inviscid, irrotational and incompressible)
- This solver is super fast and it can be used to find a solution to be used as initial conditions (non-uniform field) for an incompressible solver.
- A good initial condition will accelerate and improve the convergence rate.
- This case is already setup in the directory

#### \$PTOFC/1010F/vortex\_shedding/c4

- Do not forget to explore the dictionary files.
- The following dictionaries are different
  - system/fvSchemes
  - system/fvSolution

Try to spot the differences.

#### Running the case – Let us use a potential solver to find a quick solution

- You will find this tutorial in the directory **\$PTOFC/1010F/vortex\_shedding/c4**
- Feel free to use the Fluent mesh or the mesh generated with blockMesh. In this case we will use blockMesh.
- To run this case, in the terminal window type:
  - 1. \$> foamCleanTutorials
  - 2. \$> blockMesh
  - 3. \$> rm -rf 0
  - 4. | \$> cp -r 0\_org 0
  - 5. \$> potentialFoam -noFunctionObjects -initialiseUBCs -writep -writePhi
  - 6. \$> paraFoam

#### Running the case – Let us use a potential solver to find a quick solution

- In step 2 we generate the mesh using blockMesh. The name and type of the patches are already set in the dictionary blockMeshDict so there is no need to modify the *boundary* file.
- In step 4 we copy the original files to the directory 0. We do this to keep a backup of the original files as they will be overwritten by the solver potentialFoam.
- In step 5 we run the solver. We use the option -noFunctionObjects to avoid conflicts with the functionobjects. The options -writep and -writePhi will write the pressure field and fluxes respectively.
- At this point, if you want to use this solution as initial conditions for an incompressible solver, just copy the files U and p into the start directory of the incompressible case you are looking to run. Have in mind that the meshes need to be the same.
- Be careful with the **name** and **type** of the boundary conditions, they should be same between the potential case and incompressible case.

#### **Potential solution**

- Using a potential solution as initial conditions is much better than using a uniform flow. It will speed up the solution and it will give you more stability.
- Finding a solution using the potential solver is inexpensive.



Velocity field

Pressure field

#### The output screen

- This is the output screen of the potentialFoam solver.
- The output of this solver is also a good indication of the sensitivity of the mesh quality to gradients computation. If you see that the number of iterations are dropping iteration after iteration, it means that the mesh is fine.
- If the number of iterations remain stalled, it means that the mesh is sensitive to gradients, so should use non-orthogonal correction.
- In this case we have a good mesh.


#### Let us map a solution from a coarse mesh to a finer mesh

- It is also possible to map the solution from a coarse mesh to a finer mesh (and all the way around).
- For instance, you can compute a full Navier Stokes solution in a coarse mesh (fast solution), and then map it to a finer mesh.
- Let us map the solution from the potential solver to a finer mesh (if you want you can map the solution obtained using icoFoam). To do this we will use the utility mapFields.
- This case is already setup in the directory

\$PTOFC/1010F/vortex\_shedding/c6

#### Running the case – Let us map a solution from a coarse mesh to a finer mesh

- You will find this tutorial in the directory **\$PTOFC/1010F/vortex\_shedding/c6**
- To generate the mesh, use blockMesh (remember this mesh is finer).
- To run this case, in the terminal window type:

```
1. $> foamCleanTutorials
```

```
2. $> blockMesh
```

```
3. $> rm -rf 0
```

```
4. | $> cp -r 0_org 0
```

```
5. $> mapfields ../c4 -consistent -noFunctionObjects -mapMethod cellPointInterpolate -sourceTime 0
```

5. |\$> paraFoam

#### Running the case – Let us map a solution from a coarse mesh to a finer mesh

- In step 2 we generate a finer mesh using blockMesh. The name and type of the patches are already set in the dictionary blockMeshDict so there is no need to modify the boundary file.
- In step 4 we copy the original files to the directory 0. We do this to keep a backup of the original files as they will be overwritten by the utility mapFields.
- In step 5 we use the utility mapFields with the following options:
  - We copy the solution from the directory  $\ldots / c4$
  - The options -consistent is used when the domains and BCs are the same.
  - The option -noFunctionObjects is used to avoid conflicts with the functionObjects.
  - The option -mapMethod cellPointInterpolate defines the interpolation method.
  - The option -sourceTime 0 defines the time from which we want to interpolate the solution.

#### The meshes and the mapped fields



#### The output screen

- This is the output screen of the mapFields utility.
- The utility mapFields, will try to interpolate all fields in the source directory.
- You can control the target time via the startFrom and startTime keywords in the *controlDict* dictionary file.



#### Setting a turbulent case

- So far we have used laminar incompressible solvers.
- Let us do a turbulent simulation.
- When doing turbulent simulations, we need to choose the turbulence model, define the boundary and initial conditions for the turbulent quantities, and modify the fvSchemes and fvSolution dictionaries to take account for the new variables we are solving (the transported turbulent quantities).
- This case is already setup in the directory

\$PTOFC/1010F/vortex\_shedding/c14

- The following dictionaries remain unchanged
  - system/blockMeshDict
  - constant/polyMesh/boundary
  - 0/p
  - 0/U
- The following dictionaries need to be adapted for the turbulence case
  - constant/transportProperties
  - system/controlDict
  - system/fvSchemes
  - system/fvSolution
- The following dictionaries need to be adapted for the turbulence case
  - constant/turbulenceProperties

The transportProperties dictionary file

- This dictionary file is located in the directory constant.
- In this file we set the transport model and the kinematic viscosity (**nu**).

16	transportModel	Newtonian;	
17			
19	nu	nu [ 0 2 -1 0 0 0 0 ] 0.0002;	

• Reminder:

|**≞**]

- The diameter of the cylinder is 2.0 m.
- And we are targeting for a Re = 10000.

$$\nu = \frac{\mu}{\rho}$$
  $Re = \frac{\rho \times U \times D}{\mu} = \frac{U \times D}{\nu}$ 

The turbulenceProperties dictionary file

- This dictionary file is located in the directory **constant**.
- In this dictionary file we select what model we would like to use (laminar or turbulent).
- In this case we are interested in modeling turbulence, therefore the dictionary is as follows



• If you want to know the models available use the banana method.

### The controlDict dictionary

17	application	<pre>pimpleFoam;</pre>
18		
20	startFrom	latestTime;
21		
22	startTime	0;
23		
24	stopAt	endTime;
25		
26	endTime	500;
27		
28	deltaT	0.001;
32		
33	writeControl	runTime;
41		
42	writeInterval	1;
43		
50	purgeWrite	0;
51		
52	writeFormat	ascii;
53		
54	writePrecision	8;
55		
56	writeCompressio	on off;
57		
58	timeFormat	general;
59		
60	timePrecision	6;
61		
62	runTimeModifiab	le yes;
63		
64	adjustTimeStep	yes;
65	•	-
66	maxCo	0.9;
67	maxDeltaT	0.1;

|≞]

- This case will start from the last saved solution (**startFrom**). If there is no solution, the case will start from time 0 (**startTime**).
- It will run up to 500 seconds (endTime).
- The initial time step of the simulation is 0.001 seconds (deltaT).
- It will write the solution every 1 second (writeInterval) of simulation time (runTime).
- It will keep all the solution directories (purgeWrite).
- It will save the solution in ascii format (writeFormat).
- The write precision is 8 digits (writePrecision).
- And as the option **runTimeModifiable** is on, we can modify all these entries while we are running the simulation.
- In line 64 we turn on the option **adjustTimeStep**. This option will automatically adjust the time step to achieve the maximum desired courant number **maxCo** (line 66).
- We also set a maximum time step maxDeltaT in line 67.
- Remember, the first time step of the simulation is done using the value set in line 28 and then it is automatically scaled to achieve the desired maximum values (lines 66-67).
- The feature **adjustTimeStep** is only present in the **PIMPLE** family solvers, but it can be added to any solver by modifying the source code.

The *fvSchemes* dictionary

```
17
      ddtSchemes
18
      ſ
21
          default
                           CrankNicolson 0.5;
22
      }
24
      gradSchemes
25
      £
31
          default
                            cellLimited leastSquares 1;
36
                            cellLimited Gauss linear 1;
          grad(U)
37
      ł
39
      divSchemes
40
      {
41
          default
                           none;
47
          div(phi,U)
                           Gauss linearUpwindV grad(U);
49
          div((nuEff*dev2(T(grad(U))))) Gauss linear;
51
          div(phi,k)
                               Gauss linearUpwind default;
52
          div(phi,omega)
                               Gauss linearUpwind default;
63
      }
65
      laplacianSchemes
66
      {
74
           default
                            Gauss linear limited 1;
75
      ł
77
      interpolationSchemes
78
      {
79
          default.
                           linear;
81
      ł
83
      snGradSchemes
84
      {
86
          default
                           limited 1;
87
      }
89
      wallDist
90
      ſ
91
          method meshWave;
92
      1
```

- In this case, for time discretization (ddtSchemes) we are using the blended CrankNicolson method. The blending coefficient goes from 0 to 1, where 0 is equivalent to the Euler method and 1 is a pure Crank Nicolson.
- For gradient discretization (gradSchemes) we are using as default option the leastSquares method. For grad(U) we are using Gauss linear with slope limiters (cellLimited). You can define different methods for every term in the governing equations, for example, you can define a different method for grad(p).
- For the discretization of the convective terms (divSchemes) we are using linearUpwindV interpolation method with slope limiters for the term div(phi,U).
- For the terms div(phi,k) and div(phi,omega) we are using linearUpwind interpolation method with no slope limiters. These terms are related to the turbulence modeling.
- For the term **div((nuEff\*dev2(T(grad(U)))))** we are using **linear** interpolation (this term is related to turbulence modeling).
- For the discretization of the Laplacian (laplacianSchemes and snGradSchemes) we are using the Gauss linear limited 1 method.
- To compute the distance to the wall and normals to the wall, we use the method **meshWave**. This only applies when using wall functions (turbulence modeling).
- This method is second order accurate.

### The fvSolution dictionary

```
17
       solvers
18
       £
31
           р
32
            ł
33
                solver
                                  GAMG ;
34
                tolerance
                                  1e-6;
35
                relTol
                                  0.001;
36
                smoother
                                  GaussSeidel;
37
                nPreSweeps
                                  0:
38
                nPostSweeps
                                  2;
39
                cacheAgglomeration on;
40
                agglomerator
                                  faceAreaPair;
41
                nCellsInCoarsestLevel 100;
42
                mergeLevels
                                  1;
44
                minIter
                                2:
45
            }
46
47
            pFinal
48
            {
49
                solver
                                 PCG:
50
                preconditioner DIC;
51
                tolerance
                                 1e-06;
52
                relTol
                                 0;
54
                minIter
                                3;
55
            }
56
57
            υ
58
            ł
59
                                 PBiCGStab:
                solver
60
                preconditioner DILU;
61
                                 1e-08;
                tolerance
62
                relTol
                                 0:
63
                minIter
                                3;
64
            ł
```

|**=**]

- To solve the pressure (p) we are using the GAMG method, with an absolute tolerance of 1e-6 and a relative tolerance relTol of 0.001. Notice that we are fixing the number of minimum iterations (miniter).
- To solve the final pressure correction (**pFinal**) we are using the **PCG** method with the **DIC** preconditioner, with an absolute **tolerance** of 1e-6 and a relative tolerance **reIToI** of 0.
- Notice that we can use different methods between **p** and **pFinal**. In this case we are using a tighter tolerance for the last iteration.
- We are also fixing the number of minimum iterations (**miniter**). This entry is optional.
- To solve **U** we are using the solver **PBiCGStab** with the **DILU** preconditioner, an absolute **tolerance** of 1e-8 and a relative tolerance **reITol** of 0. Notice that we are fixing the number of minimum iterations (**minIter**).

### The fvSolution dictionary

1.7			
17	solvers	3	
18	{		
77	01:1	.nal	
78	ł		
79		solver	PBiCGStab;
80		preconditioner	DILU;
81		tolerance	1e-08;
82		relTol	0;
83		minIter	3;
84	}		
85			
86	ome	ega	
87	۱		
88		solver	PBICGStad;
00		preconditioner	
90		tolerance	10-08;
91		reitoi	0; 2.
92	1	miniter	5,
95	3		
95	0.000	GaFinal	
95	ſ	igarinai	
97	ι ι	solver	PBiCGStab:
98		preconditioner	DTLU:
99		tolerance	1e-08:
100		relTol	0:
101		minIter	3:
102	}		- ,
103			
104	k		
105	{		
106		solver	PBiCGStab;
107		preconditioner	DILU;
108		tolerance	1e-08;
109		relTol	0;
110		minIter	3;
111	}		

|≞]

- To solve **UFinal** we are using the solver **PBiCGStab** with an absolute **tolerance** of 1e-8 and a relative tolerance **reITol** of 0. Notice that we are fixing the number of minimum iterations (**miniter**).
- To solve **omega** and **omegaFinal** we are using the solver **PBiCGStab** with an absolute **tolerance** of 1e-8 and a relative tolerance **reITol** of 0. Notice that we are fixing the number of minimum iterations (**miniter**).
- To solve **k** we are using the solver **PBiCGStab** with an absolute **tolerance** of 1e-8 and a relative tolerance **relTol** of 0. Notice that we are fixing the number of minimum iterations (**miniter**).

### The fvSolution dictionary

		kFi	nal	
114		{		
115			solver	<pre>PBiCGStab;</pre>
116			preconditioner	DILU;
117			tolerance	1e-08;
118			relTol	0;
119			minIter	3;
120		}		
121	}			
122				
L23	PIN	IPLE		
L24	{			
126			nOuterCorrector	s 1;
127			//nOuterCorrect	ors 2;
128				
129			nCorrectors 3;	
130			nNonOrthogonalC	correctors 1;
L33	}			
134				_
135	rel	axat	ionFactors	
136	{			
137		fie	elds	
138		{		
139			P	0.3;
140		}		
141		equ	ations	,
142		{		
143			U	0.7;
144			k	0.7;
145			omega	0.7;
		}		
146				

|≞]

- To solve **kFinal** we are using the solver **PBiCGStab** with an absolute **tolerance** of 1e-8 and a relative tolerance **reITol** of 0. Notice that we are fixing the number of minimum iterations (**miniter**).
- In lines 123-133 we setup the entries related to the pressure-velocity coupling method used (PIMPLE in this case). Setting the keyword nOuterCorrectors to 1 is equivalent to running using the PISO method.
- To gain more stability we are using 1 outer correctors (nOuterCorrectors), 3 inner correctors or PISO correctors (nCorrectors), and 1 correction due to non-orthogonality (nNonOrthogonalCorrectors).
- Remember, adding corrections increase the computational cost.
- In lines 135-147 we setup the under relaxation factors used during the outer corrections (pseudo transient iterations). If you are working in **PISO** mode (only one outer correction or **nOuterCorrectors**), these values are ignored.

- The following dictionaries are new
  - 0/k
  - 0/omega
  - 0/nut

These are the field variables related to the closure equations of the turbulent model.

- As we are going to use the  $\kappa \omega SST$  model we need to define the initial conditions and boundaries conditions.
- To define the IC/BC we will use the free stream values of  $\kappa$  and  $\omega$
- In the following site, you can find a lot information abut choosing initial and boundary conditions for the different turbulence models:
  - https://turbmodels.larc.nasa.gov/

### $\kappa-\omega\;SST\;$ Turbulence model free-stream boundary conditions

• The initial value for the turbulent kinetic energy  $\kappa$  can be found as follows

$$\kappa = \frac{3}{2}(UI)^2$$

- The initial value for the specific kinetic energy  $\,\,\omega\,\,$  can be found as follows

$$\omega = \frac{\rho \kappa}{\mu} \frac{\mu_t}{\mu}^{-1}$$

• Where  $\frac{\mu_t}{\mu}$  is the viscosity ratio and  $I = \frac{u'}{\overline{u}}$  is the turbulence intensity.

 If you are working with external aerodynamics or virtual wind tunnels, you can use the following reference values for the turbulence intensity and the viscosity ratio. They work most of the times, but it is a good idea to have some experimental data or a better initial estimate.

	Low	Medium	High
Ι	1.0 %	5.0 %	10.0 %
$\mu_t/\mu$	1	10	100

-

|≞1

The file 0/k

19	internalField	uniform	0.00015;
20			
21	boundaryField		
22	{		
23	out		
24	{		
25	type		<pre>inletOutlet;</pre>
26	inletVal	ue	uniform 0.00015;
27	value		uniform 0.00015;
28	}		
29	sym1		
30	{		
31	type		<pre>symmetryPlane;</pre>
32	}		
33	sym2		
34	ł		
35	type		<pre>symmetryPlane;</pre>
36	}		
37	in		
38	ł		
39	type		<pre>fixedValue;</pre>
40	value		uniform 0.00015;
41	}		
42	cylinder		
43	ł		
44	type		kqRWallFunction;
45	value		uniform 0.00015;
46	}		
47	back		
48	{		
49	type		empty;
50	}		
51	front		
52	{		
53	type		empty;
54	}		
55	}		

- We are using uniform initial conditions (line 19).
- For the **in** patch we are using a **fixedValue** boundary condition.
- For the **out** patch we are using an **inletOutlet** boundary condition (this boundary condition avoids backflow).
- For the **cylinder** patch (which is **base type wall**), we are using the **kqRWallFunction** boundary condition. This is a wall function, we are going to talk about this when we deal with turbulence modeling. Remember, we can use wall functions only if the patch is of **base type wall**.
- The rest of the patches are constrained.
- FYI, the inlet velocity is 1 and the turbulence intensity is equal to 1%.

### The file 0/omega

|≡]

19	internalFie	id uniform	0.075;
20			
21	boundaryFie	ld	
22	{		
23	out		
24	{		
25	typ	e	inletOutlet;
26	inl	etValue	uniform 0.075;
27	val	ue	uniform 0.075;
28	}		
29	syml		
30	{		
31	typ	e	<pre>symmetryPlane;</pre>
32	}		
33	sym2		
34	{		
35	typ	e	<pre>symmetryPlane;</pre>
36	}		
37	in		
38	{		
39	typ	e	fixedValue;
40	val	ue	uniform 0.075;
41	}		
42	cylinde	r	
43	{		
44	typ	e	omegaWallFunction;
45	Cmu	L	0.09;
46	kap	pa	0.41;
47	E		9.8;
48	bet	al	0.075;
49	val	ue	uniform 0.075;
50	}		
51	back		
52	{		
53	typ	e	empty;
54	}		
55	front		
56	{		
57	typ	e	empty;
58	}		
59	}		

- We are using uniform initial conditions (line 19).
- For the **in** patch we are using a **fixedValue** boundary condition.
- For the **out** patch we are using an **inletOutlet** boundary condition (this boundary condition avoids backflow).
- For the **cylinder** patch (which is **base type wall**), we are using the **omegaWallFunction** boundary condition. This is a wall function, we are going to talk about this when we deal with turbulence modeling. Remember, we can use wall functions only if the patch is of **base type wall**.
- The rest of the patches are constrained.
- FYI, the inlet velocity is 1 and the eddy viscosity ratio is equal to 10.

### The file 0/nut

|≡]

19	internalField	uniform 0;
20		
21	boundaryField	
22	{	
23	out	
24	{	
25	type	calculated;
26	value	uniform 0;
27	}	
28	sym1	
29	{	
30	type	symmetryPlane;
31	}	
32	sym2	
33	{	
34	type	symmetryPlane;
35	}	
36	in	
37	{	
38	type	calculated;
39	value	uniform 0;
40	}	
41	cylinder	
42	1	
43	type	nutkwallFunction;
44	Cmu	0.09;
45	карра	0.41;
40	<u>-</u>	9.0;
47	varue l	difform 0,
40	back	
50	1	
51	type	empty:
52	}	
53	front	
54	{	
55	type	empty;
56	}	
57	}	

- We are using uniform initial conditions (line 19).
- For the **in** patch we are using the **calculated** boundary condition (nut is computed from kappa and omega)
- For the **out** patch we are using the **calculated** boundary condition (nut is computed from kappa and omega)
- For the cylinder patch (which is base type wall), we are using the nutkWallFunction boundary condition. This is a wall function, we are going to talk about this when we deal with turbulence modeling. Remember, we can use wall functions only if the patch is of base type wall.
- The rest of the patches are constrained.
- Remember, the turbulent viscosity  $\nu_t$  (nut) is equal to

 $\kappa$ 

ω

### Running the case – Setting a turbulent case

- You will find this tutorial in the directory **\$PTOFC/1010F/vortex\_shedding/c14**
- Feel free to use the Fluent mesh or the mesh generated with blockMesh. In this case we will use blockMesh.
- To run this case, in the terminal window type:

```
$> foamCleanTutorials
1.
2.
      $> blockMesh
3.
      $> renumberMesh -overwrite
      $> pimpleFoam | log
4.
      You will need to launch this script in a different terminal
      $> pyFoamPlotWatcher.py log
5.
      You will need to launch this script in a different terminal
      $> gnuplot scripts0/plot coeffs
6.
      You will need to launch this script in a different terminal
7.
      $> pimpleFoam -postprocess -func yPlus -latestTime -noFunctionObjects
8.
          paraFoam
```

### Running the case – Setting a turbulent case

- In step 3 we use the utility renumberMesh to make the linear system more diagonal dominant, this will speed-up the linear solvers.
- In step 4 we run the simulation and save the log file. Notice that we are sending the job to background.
- In step 5 we use pyFoamPlotWatcher.py to plot the residuals on-the-fly. As the job is running in background, we can launch this utility in the same terminal tab.
- In step 6 we use the gnuplot script scripts0/plot\_coeffs to plot the force coefficients on-the-fly. Besides monitoring the residuals, is always a good idea to monitor a quantity of interest. Feel free to take a look at the script and to reuse it.
- In step 7 we use the utility postProcess to compute the  $y^+$  value of each saved solution (we are going to talk about  $y^+$  when we deal with turbulence modeling).



#### The output screen

• This is the output screen of the yPlus utility.



#### Using a compressible solver

- So far we have only used incompressible solvers.
- Let us use the compressible solver rhoPimpleFoam, which is a

Transient solver for laminar or turbulent flow of compressible fluids for HVAC and similar applications. Uses the flexible PIMPLE (PISO-SIMPLE) solution for time-resolved and pseudo-transient simulations.

- When working with compressible solver we need to define the thermodynamical properties of the working fluid and the temperature field (we are also solving the energy equation)
- This case is already setup in the directory

\$PTOFC/1010F/vortex\_shedding/c24

- The following dictionaries remain unchanged
  - system/blockMeshDict
  - constant/polyMesh/boundary

- Reminder:
  - The diameter of the cylinder is 0.002 m.
  - The working fluid is air at 20° Celsius and at a sea level.
  - Isothermal flow.
  - And we are targeting for a Re = 200.

$$\nu = \frac{\mu}{\rho} \qquad Re = \frac{\rho \times U \times D}{\mu} = \frac{U \times D}{\nu}$$

The constant directory

- In this directory, we will find the following compulsory dictionary files:
  - thermophysicalProperties
  - turbulenceProperties
- thermophysicalProperties contains the definition of the physical properties of the working fluid.
- turbulenceProperties contains the definition of the turbulence model to use.

### The thermophysicalProperties dictionary file



- This dictionary file is located in the directory **constant**. Thermophysical models are concerned with energy, heat and physical properties.
- In the sub-dictionary thermoType (lines 18-27), we define the thermophysical models.
- The **transport** modeling concerns evaluating dynamic viscosity (line 22). In this case the viscosity is constant.
- The thermodynamic models (**thermo**) are concerned with evaluating the specific heat Cp (line 23). In this case Cp is constant
- The **equationOfState** keyword (line 24) concerns to the equation of state of the working fluid. In this case

$$\rho = \frac{p}{RT}$$

 The form of the energy equation to be used in the solution is specified in line 26 (energy). In this case we are using enthalpy (sensibleEnthalpy).

The thermophysicalProperties dictionary file

8	thermoType	
•	{	
)	type	hePsiThermo;
L	mixture	<pre>pureMixture;</pre>
2	transport	const;
3	thermo	hConst;
4	equationOfState	perfectGas;
5	specie	specie;
6	energy	<pre>sensibleEnthalpy;</pre>
7	}	
8		
9	mixture	
0	{	
1	specie	
2	{	
3	nMoles	1;
4	molWeight	28.9;
5	}	
6	thermodynamics	
7	{	
8	Cp	1005;
9	Hf	0;
0	}	
1	transport	
2	{	
2	mu	1.84e-05;
3	D-+	0.713;
14	Pr	
4 5	}	

- In the sub-dictionary **mixture** (lines 29-46), we define the thermophysical properties of the working fluid.
- In this case, we are defining the properties for air at 20° Celsius and at a sea level.

The turbulenceProperties dictionary file

- In this dictionary file we select what model we would like to use (laminar or turbulent).
- This dictionary is compulsory.

|≞1

• As we do not want to model turbulence, the dictionary is defined as follows,

17 simulationType laminar;

### The 0 directory

- In this directory, we will find the dictionary files that contain the boundary and initial conditions for all the primitive variables.
- As we are solving the compressible laminar Navier-Stokes equations, we will find the following field files:
  - p (pressure)
  - T (temperature)
  - U (velocity field)

### The file 0/p

17	dimensions	[1 -1 -2 0 0 0 0];
18		
19	internalField	uniform 101325;
20		
21	boundaryField	
22	{	
23	in	
24	{	
25	type	<pre>zeroGradient;</pre>
26	}	
28	out	
29	{	
30	type	<pre>fixedValue;</pre>
31	value	uniform 101325;
32	}	
34	cylinder	
35	{	
36	type	<pre>zeroGradient;</pre>
37	}	
39	sym1	
40	{	
41	type	<pre>symmetryPlane;</pre>
42	}	
44	sym2	
45	{	
46	type	<pre>symmetryPlane;</pre>
47	}	
49	back	
50	{	
51	type	empty;
52	}	
54	front	
55	{	
56	type	empty;
57	}	
58	}	

- This file contains the boundary and initial conditions for the scalar field pressure (p). We are working with absolute pressure.
- Contrary to incompressible flows where we defined relative pressure, this is the absolute pressure.
- Also, pay attention to the units (line 17). The pressure is defined in Pascal.
- We are using uniform initial conditions (line 19).
- For the **in** patch we are using a **zeroGradient** boundary condition.
- For the **outlet** patch we are using a **fixedValue** boundary condition.
- For the **cylinder** patch we are using a **zeroGradient** boundary condition.
- The rest of the patches are constrained.

The file 0/T

17	dimensions	[0 0 0 -1 0 0 0];
18		
19	internalField	uniform 293.15;
20	h ann da matri a 1 d	
21	foundaryField	
22	1 in	
23	111	
25	1	fixedValue
25	value	\$internalField:
20	varue 1	çinternarrieta,
29	out	
30	1	
31	type	inletOutlet:
32	value	SinternalField:
33	inletVa	lue \$internalField;
34	}	• • • • • •
36	cylinder	
37	-	
38	type	<pre>zeroGradient;</pre>
39	}	
41	sym1	
42	{	
43	type	<pre>symmetryPlane;</pre>
44	}	
46	sym2	
47	{	
48	type	symmetryPlane;
49	}	
51	back	
52	{	
53	type	empty;
54	}	
56	front	
57	{	
58	type	empty;
59	}	
60	}	

- This file contains the boundary and initial conditions for the scalar field temperature (**T**).
- Also, pay attention to the units (line 17). The temperature is defined in Kelvin.
- We are using uniform initial conditions (line 19).
- For the **in** patch we are using a **fixedValue** boundary condition.
- For the **out** patch we are using a **inletOutlet** boundary condition (in case of backflow).
- For the **cylinder** patch we are using a **zeroGradient** boundary condition.
- The rest of the patches are constrained.

The file 0/U

|**=**]

```
17
      dimensions
                        [0 1 - 1 0 0 0 0];
18
19
      internalField uniform (1.5 0 0);
20
21
      boundaryField
22
      ſ
23
           in
24
           {
25
                                 fixedValue;
               type
26
                                 uniform (1.5 0 0);
               value
27
           }
29
           out
30
           {
31
                                 inletOutlet;
                type
32
                phi
                                 phi;
33
                inletValue
                                 uniform (0 \ 0 \ 0);
34
                value
                                 uniform (0 \ 0 \ 0);
35
           }
37
           cylinder
38
           ſ
39
                                 fixedValue;
               type
40
               value
                                 uniform (0 0 0);
41
           }
43
           sym1
44
           {
45
               type
                                 symmetryPlane;
46
           ł
48
           sym2
49
           {
50
               type
                                 symmetryPlane;
51
           }
53
           back
54
           {
55
               type
                                 empty;
56
           }
58
           front
59
           ł
60
               type
                                 empty;
61
           ł
62
```

- This file contains the boundary and initial conditions for the dimensional vector field **U**.
- We are using uniform initial conditions and the numerical value is (1.5 0 0) (keyword internalField in line 19).
- For the **in** patch we are using a **fixedValue** boundary condition.
- For the **out** patch we are using a **inletOutlet** boundary condition (in case of backflow).
- For the **cylinder** patch we are using a **zeroGradient** boundary condition.
- The rest of the patches are constrained.

The system directory

- The **system** directory consists of the following compulsory dictionary files:
  - controlDict
  - fvSchemes
  - fvSolution
- *controlDict* contains general instructions on how to run the case.
- *fvSchemes* contains instructions for the discretization schemes that will be used for the different terms in the equations.
- *fvSolution* contains instructions on how to solve each discretized linear equation system.

### The controlDict dictionary

17	application	icoFoam;
18		
19	startFrom	<pre>startTime;</pre>
20	//startFrom	<pre>latestTime;</pre>
21		
22	startTime	0;
23		
24	stopAt	endTime;
25	//stopAt write	Now;
26		
27	endTime	0.3;
28		
29	deltaT	0.00001;
30		
31	writeControl	<pre>adjustableRunTime;</pre>
32		
33	writeInterval	0.0025;
34		
35	purgeWrite	0;
36		
37	writeFormat	ascii;
38		
39	writePrecision	10;
40		
41	writeCompressio	n off;
42		
43	timeFormat	general;
44	1. i	
45	timePrecision	<b>b</b> ;
46		1
47	runTimeModifiab	le true;
48		
49	adjust1'imeStep	yes;
50	maxCo	1;
51	maxDeltaT	1;

- This case will start from the last saved solution (**startFrom**). If there is no solution, the case will start from time 0 (**startTime**).
- It will run up to 0.3 seconds (endTime).
- The initial time step of the simulation is 0.00001 seconds (deltaT).
- It will write the solution every 0.0025 seconds (writeInterval) of simulation time (adjustableRunTime). The option adjustableRunTime will adjust the time-step to save the solution at the precise intervals. This may add some oscillations in the solution as the CFL is changing.
- It will keep all the solution directories (purgeWrite).
- It will save the solution in ascii format (writeFormat).
- And as the option **runTimeModifiable** is on, we can modify all these entries while we are running the simulation.
- In line 49 we turn on the option **adjustTimeStep**. This option will automatically adjust the time step to achieve the maximum desired courant number (line 50).
- We also set a maximum time step in line 51.
- Remember, the first time step of the simulation is done using the value set in line 28 and then it is automatically scaled to achieve the desired maximum values (lines 66-67).
- The feature **adjustTimeStep** is only present in the **PIMPLE** family solvers, but it can be added to any solver by modifying the source code.

### The controlDict dictionary

```
55
       functions
56
       {
178
       forceCoeffs object
179
       £
188
        type forceCoeffs;
189
        functionObjectLibs ("libforces.so");
190
       patches (cylinder);
191
192
        pName p;
193
        Uname U;
194
        //rhoName rhoInf;
195
        rhoInf 1.205;
196
197
       //// Dump to file
198
        log true;
199
200
       CofR (0.0 0 0);
201
        liftDir (0 1 0);
202
        dragDir (1 \ 0 \ 0);
203
        pitchAxis (0 0 1);
204
        magUInf 1.5;
        lRef 0.001;
205
206
       Aref 0.000002;
207
208
        outputControl
                         timeStep;
209
        outputInterval 1;
210
        ł
235
236
       };
```

|≞]

- As usual, at the bottom of the *controlDict* dictionary file we define the **functionObjects** (lines 55-236).
- Of special interest is the functionObject forceCoeffs\_object.
- As we changed the domain dimensions and the inlet velocity we need to update the reference values (lines 204-206).
- It is also important to update the reference density (line 195).
#### The fvSchemes dictionary

```
17
      ddtSchemes
18
      {
19
          default
                            Euler;
20
      }
21
22
      gradSchemes
23
      {
29
          default.
                             cellLimited leastSquares 1;
34
      ł
35
36
      divSchemes
37
      ſ
38
          default
                           none;
39
          div(phi,U)
                            Gauss linearUpwindV default;
40
41
                            Gauss linear;
          div(phi,K)
42
          div(phi,h)
                            Gauss linear;
43
44
          div(((rho*nuEff)*dev2(T(grad(U))))) Gauss linear;
45
      }
46
47
      laplacianSchemes
48
      {
49
          default
                           Gauss linear limited 1;
50
      ł
51
52
      interpolationSchemes
53
      ſ
54
          default
                            linear;
55
      }
56
57
      snGradSchemes
58
      {
59
          default
                           limited 1;
60
```

|≞1

- In this case, for time discretization (ddtSchemes) we are using the Euler method.
- For gradient discretization (gradSchemes) we are using the leastSquares method.
- For the discretization of the convective terms (divSchemes) we are using linearUpwind interpolation with no slope limiters for the term div(phi,U).
- For the terms div(phi,K) (kinetic energy) and div(phi,h) (enthalpy) we are using linear interpolation method with no slope limiters.
- For the term div(((rho\*nuEff)\*dev2(T(grad(U))))) we are using linear interpolation (this term is related to the turbulence modeling).
- For the discretization of the Laplacian (laplacianSchemes and snGradSchemes) we are using the Gauss linear limited 1 method.
- This method is second order accurate.

### The fvSolution dictionary

17	solvers		
18	{		
20	а		
21	-		
22	•	solver	PCG;
23		preconditioner	DIC;
24		tolerance	1e-06;
25		relTol	0.01;
26		minIter	2;
27	}		
46	pFinal		
47	{		
48		\$p;	
49		relTol	0;
50		minIter	2;
51	}		
53	"U.	*"	
54	ł		
55		solver	PBiCGStab;
56		preconditioner	DILU;
57		tolerance	1e-08;
58		relTol	0;
59		minIter	2;
60	}		
74	hFi	nal	
75	{		
76		solver	PBiCGStab;
77		preconditioner	DILU;
78		tolerance	1e-08;
79		relTol	0;
80	_	minIter	2;
81	}		
83	"rh	0.*"	
84	ł		
85	,	solver	diagonal;
86	, ,		
87	ł		

|≞]

- To solve the pressure (**p**) we are using the **PCG** method with an absolute **tolerance** of 1e-6 and a relative tolerance **reITol** of 0.01.
- The entry pFinal refers to the final correction of the PISO loop. Notice that we are using macro expansion (\$p) to copy the entries from the sub-dictionary p.
- To solve U and UFinal (U.\*) we are using the solver PBiCGStab with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0.
- To solve hFinal (enthalpy) we are using the solver PBiCGStab with an absolute tolerance of 1e-8 and a relative tolerance relTol of 0.
- To solve **rho** and **rhoFinal** (**rho.**\*) we are using the **diagonal** solver (remember rho is found from the equation of state, so this is a back-substitution).
- FYI, solving for the velocity is relative inexpensive, whereas solving for the pressure is expensive.
- Be careful with the enthalpy, it might cause oscillations.

### The fvSolution dictionary

88				
89	PIMPLE			
90	{			
91	momentumPredi	momentumPredictor yes;		
92	nOuterCorrect	nOuterCorrectors 1;		
93	nCorrectors	2;		
94	nNonOrthogona	<pre>nNonOrthogonalCorrectors 1;</pre>		
95	rhoMin	0.5;		
96	rhoMax	2.0;		
97	}			

|≞]

- The **PIMPLE** sub-dictionary contains entries related to the pressure-velocity coupling (in this case the **PIMPLE** method).
- Setting the keyword nOuterCorrectors to 1 is equivalent to running using the PISO method.
- Hereafter we are doing 2 PISO correctors (nCorrectors) and 1 non-orthogonal corrections (nNonOrthogonalCorrectors).
- In lines 95-96 we set the minimum and maximum physical values of rho (density).
- If we increase the number of nCorrectors and nNonOrthogonalCorrectors we gain more stability but at a higher computational cost.
- The choice of the number of corrections is driven by the quality of the mesh and the physics involve.
- You need to do at least one **PISO** loop (**nCorrectors**).

#### Running the case – Using a compressible solver

- You will find this tutorial in the directory **\$PTOFC/1010F/vortex\_shedding/c24**
- Feel free to use the Fluent mesh or the mesh generated with blockMesh. In this case we will use blockMesh.
- To run this case, in the terminal window type:
  - 1. \$> foamCleanTutorials
  - 2. \$> blockMesh
  - 3. \$> transformPoints -scale `(0.001 0.001 0.001)'
  - 4. \$> renumberMesh -overwrite
  - 5. \$> rhoPimpleFoam | tee log
    - \$> pyFoamPlotWatcher.py log

You will need to launch this script in a different terminal

\$> gnuplot scripts0/plot\_coeffs

You will need to launch this script in a different terminal

- 8. \$> rhoPimpleFoam -postProcess -func MachNo
- 9. \$> paraFoam

6.

7.

#### Running the case – Using a compressible solver

- In step 3 we scale the mesh.
- In step 4 we use the utility renumberMesh to make the linear system more diagonal dominant, this will speed-up the linear solvers.
- In step 5 we run the simulation and save the log file. Notice that we are sending the job to background.
- In step 6 we use pyFoamPlotWatcher.py to plot the residuals on-the-fly. As the job is running in background, we can launch this utility in the same terminal tab.
- In step 7 we use the gnuplot script scripts0/plot\_coeffs to plot the force coefficients on-the-fly. Besides monitoring the residuals, is always a good idea to monitor a quantity of interest. Feel free to take a look at the script and to reuse it.
- In step 8 we use the utility MachNo to compute the Mach number.



- In the directory **\$PTOFC/101OF/vortex\_shedding**, you will find 28 variations of the cylinder case involving different solvers and models. Feel free to explore all them.
- This is what you will find in each directory,
  - c1 = blockMesh icoFoam Re = 200.
  - c2 = fluentMeshToFoam icoFoam Re = 200.
  - c3 = blockMesh icoFoam Field initialization Re = 200.
  - c4 = blockMesh potentialFoam Re = 200.
  - c5 = blockMesh mapFields icoFoam original mesh Re = 200.
  - c6 = blockMesh mapFields icoFoam Finer mesh Re = 200.
  - c7 = blockMesh pimpleFoam Re = 200 No turbulent model.
  - c8 = blockMesh pisoFoam Re = 200 No turbulent model.
  - c9 = blockMesh pisoFoam Re = 200 K-Omega SST turbulent model.
  - c10 = blockMesh simpleFoam Re = 200 No turbulent model.
  - c11 = blockMesh simpleFoam Re = 40 No turbulent model.
  - c12 = blockMesh pisoFoam Re = 40 No turbulent model.
  - c14 = blockMesh pimpleFoam Re = 10000 K-Omega SST turbulent model with wall functions.
  - c15 = blockMesh pimpleFoam Re = 100000 K-Omega SST turbulent model with wall functions.

- This is what you will find in each directory,
  - c16 = blockMesh simpleFoam Re = 100000 K-Omega SST turbulent model with no wall functions.
  - c17 = blockMesh simpleFoam Re = 100000 K-Omega SST turbulent model with wall functions.
  - c18 = blockMesh pisoFoam Re = 100000, LES Smagorinsky turbulent model.
  - c19 = blockMesh pimpleFoam Re = 1000000 Spalart Allmaras turbulent model with no wall functions.
  - c20 = blockMesh sonicFoam Mach = 2.0 Compressible Laminar.
  - c21 = blockMesh sonicFoam Mach = 2.0 Compressible K-Omega SST turbulent model with wall functions.
  - c22 = blockMesh pimpleFoam Re = 200 No turbulent model Source terms (momentum)
  - c23 = blockMesh pimpleFoam Re = 200 No turbulent model Source terms (scalar transport)
  - c24 = blockMesh rhoPimpleFoam Re = 200 Laminar, isothermal
  - c25 = blockMesh rhoPimpleFoam Re = 20000 Turbulent, compressible
  - c26 = blockMesh pimpleDyMFoam Re = 200 Laminar, moving cylinder (oscillating).
  - c27 = blockMesh pimpleDyMFoam/pimpleFoam Re = 200 Laminar, rotating cylinder using AMI patches.
  - c28 = blockMesh interFoam Laminar, multiphase, free surface.
  - c29 = blockMesh pimpleFoam laminar with source terms and AMR.