# snappyHexMesh

- "Automatic split hex mesher. Refines and snaps to surface."
- For complex geometries, the mesh generation utility snappyHexMesh can be used.
- The snappyHexMesh utility generates 3D meshes containing hexahedra and splithexahedra from a triangulated surface geometry in Stereolithography (STL) format.
- The mesh is generated from a dictionary file named *snappyHexMeshDict* located in the system directory and a triangulated surface geometry file located in the directory constant/triSurface.



### snappyHexMesh workflow

- To generate a mesh with snappyHexMesh we proceed as follows:
  - Generation of a background or base mesh.
  - Geometry definition.
  - Generation of a castellated mesh or cartesian mesh.
  - Generation of a snapped mesh or body fitted mesh.
  - Addition of layers close to the surfaces or boundary layer meshing.
  - Check/enforce mesh quality.



## snappyHexMesh workflow – Background mesh

- The background or base mesh can be generated using blockMesh or an external mesher.
- The following criteria must be observed when creating the background mesh:
  - The mesh must consist purely of hexes.
  - The cell aspect ratio should be approximately 1, at least near the STL surface.
  - There must be at least one intersection of a cell edge with the STL surface.



## snappyHexMesh workflow – Geometry (STL file)

- The STL geometry can be obtained from any geometry modeling tool.
- The STL file can be made up of a single surface describing the geometry, or multiple surfaces that describe the geometry.
- In the case of a STL file with multiple surfaces, we can use local refinement in each individual surface. This gives us more control when generating the mesh.
- The STL geometry is always located in the directory constant/triSurface



### snappyHexMesh workflow

- The meshing utility snappyHexMesh reads the dictionary snappyHexMeshDict located in the directory system.
- The castellation, snapping, and boundary layer meshing steps are controlled by the dictionary *snappyHexMeshDict*.
- The final mesh should be always located in the directory constant/polyMesh



### snappyHexMesh workflow

• All the volume and surface refinement is done in reference to the background or base mesh.



### snappyHexMesh workflow



- The process of generating a mesh using snappyHexMesh will be described using this figure.
- The objective is to mesh a rectangular shaped region (shaded grey in the figure) surrounding an object described by a STL surface (shaded green in the figure).
- This is an external mesh (*e.g.* for external aerodynamics). You can also generate an internal mesh (*e.g.* flow in a pipe).

### snappyHexMesh workflow



#### Step 1. Creating the background hexahedral mesh

- Before snappyHexMesh is executed the user must create a background mesh of hexahedral cells that fills the entire region as shown in the figure. This can be done by using blockMesh or any other mesher.
- The following criteria must be observed when creating the background mesh:
  - The mesh must consist purely of hexes.
  - The cell aspect ratio should be approximately 1, at least near the STL surface.
  - There must be at least one intersection of a cell edge with the STL surface.

### snappyHexMesh workflow



#### Step 2. Cell splitting at feature edges

- Cell splitting is performed according to the specification supplied by the user in the castellatedMeshControls sub-dictionary in the *snappyHexMeshDict* dictionary.
- The splitting process begins with cells being selected according to specified edge features as illustrated in the figure.
- The feature edges can be extracted from the STL geometry file using the utility surfaceFeatureExtract.

### snappyHexMesh workflow



#### Step 3. Cell splitting at surfaces

- Following feature edges refinement, cells are selected for splitting in the locality of specified surfaces as illustrated in the figure.
- The surface refinement (splitting) is performed according to the specification supplied by the user in the **refinementMeshControls** in the **castellatedMeshControls** sub-dictionary in the *snappyHexMeshDict* dictionary.

### snappyHexMesh workflow



#### Step 4. Cell removal

- Once the feature edges and surface splitting is complete, a process of cell removal begins.
- The region in which cells are retained are simply identified by a location point within the region, specified by the **locationInMesh** keyword in the castellatedMeshControls sub-dictionary in the *snappyHexMeshDict* dictionary.
- Cells are retained if, approximately speaking, 50% or more of their volume lies within the region.

### snappyHexMesh workflow



#### Step 5. Cell splitting in specified regions

- Those cells that lie within one or more specified volume regions can be further split by a region (in the figure, the rectangular region within the red rectangle).
- The information related to the refinement of the volume regions is supplied by the user in the **refinementRegions** block in the **castellatedMeshControls** sub-dictionary in the *snappyHexMeshDict* dictionary.
- This is a valid castellated or cartesian mesh that can be used for a simulation.

### snappyHexMesh workflow



#### Step 6. Snapping to surfaces

- After deleting the cells in the region specified and refining the volume mesh, the points are snapped on the surface to create a conforming mesh.
- The snapping is controlled by the user supplied information in the snapControls sub-dictionary in *snappyHexMeshDict*.
- Sometimes, the default **snapControls** options are not enough and you will need to adjust the values to get a good mesh, so it is advisable to save the intermediate steps with a high writing precision (*controlDict*).
- This is a valid snapped or body fitted mesh that can be used for a simulation.

### snappyHexMesh workflow



#### Step 7. Mesh layers

- The mesh output from the snapping stage may be suitable for simulation, although it can produce some irregular cells along boundary surfaces.
- There is an optional stage of the meshing process which introduces boundary layer meshing in selected parts of the mesh.
- This information is supplied by the user in the addLayersControls sub-dictionary in the *snappyHexMeshDict* dictionary.
- This is the final step of the mesh generation process using snappyHexMesh.
- This is a valid body fitted mesh with boundary layer meshing, that can be used for a simulation.

### snappyHexMesh in action

www.wolfdynamics.com/wiki/shm/ani.gif





- Let us study the snappyHexMesh dictionary in details.
- We are going to work with the case we just saw in action.
- You will find this case in the directory:



## Let us explore the snappyHexMeshDict dictionary.

- Open the dictionary *snappyHexMeshDict* with your favorite text editor (we use gedit).
- The dictionary *snappyHexMeshDict* consists of five main sections:

### • geometry

Definition of geometry entities to be used for meshing

### castellatedMeshControls

Definition of feature, surface and volume mesh refinement

### snapControls

Definition of surface mesh snapping and advanced parameters

### addLayersControls

Definition of boundary layer meshing and advanced parameters

### meshQualityControls

Definition of mesh quality metrics

### Let us explore the snappyHexMeshDict dictionary.





- The snappyHexMesh dictionary is made up of five sections, namely: geometry, castellatedMeshControls, snapControls, addLayersControls and meshQualityControls. Each section controls a step of the meshing process.
- In the first three lines we can turn off and turn on the different meshing steps. For example, if we want to generate a body fitted mesh with no boundary layer we should proceed as follows:

castellatedMesh true; snap true; addLayers false;

## Let us explore the snappyHexMeshDict dictionary.



- Have in mind that there are more than 70 parameters to control in snappyHexMeshDict dictionary.
- Adding the fact that there is no native GUI, it can be quite tricky to control the mesh generation process.
- Nevertheless, snappyHexMesh generates really good hexa dominant meshes.
- Hereafter, we will only comment on the most important parameters.
- The parameters that you will find in the *snappyHexMeshDict* dictionaries distributed with the tutorials, in our opinion are robust and will work most of the times.

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### Let us explore the snappyHexMeshDict dictionary.



### Let us explore the snappyHexMeshDict dictionary.



#### **Castellated mesh controls section**



- In the castellatedMeshControls section, we define the global refinement parameters, explicit feature edge refinement, surface based refinement, region-wise refinement and the material point.
- In this step, we are generating the castellated mesh.

#### Note 1:

The material point indicates where we want to create the mesh, that is, inside or outside the body to be meshed.

### Let us explore the snappyHexMeshDict dictionary.



#### **Castellated mesh controls section**



#### Note 1:

This parameter controls the transition between cell refinement levels.

#### Note 2:

This parameter controls the local curvature refinement. The higher the value, the less features it captures. For example if you use 100, it will not add refinement in high curvature areas. It also controls edge feature snapping, high values will not resolve sharp angles in surface intersections.

#### Note 3:

This file is automatically created when you use the utility surfaceFeatureExtract. The file is located in the directory constant/triSurface

### Let us explore the snappyHexMeshDict dictionary.



#### **Castellated mesh controls section**



#### Note 1:

The surface wolf was defined in the geometry section.

#### Note 2:

The region **wolflocal** was defined in the geometry section.

#### Note 3:

Named region in the STL file. This refinement is local. To use the surface refinement in the regions, the local regions must exist in STL file. We created a pointer to this region in the geometry section.

#### Note 4:

You can only define patches of type wall or patch.

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### Let us explore the snappyHexMeshDict dictionary.



#### **Castellated mesh controls section**



#### Note 1:

Optional specification of what to do with faceZone faces:

internal: keep them as internal faces (default)

**baffle:** create baffles from them. This gives more freedom in mesh motion

**boundary:** create free-standing boundary faces (baffles but without the shared points)

e.g., faceType internal;

### Let us explore the snappyHexMeshDict dictionary.



}

#### **Castellated mesh controls section**



#### Note 1:

This region or geometrical entity was created in the geometry section.

### At this point we have a valid mesh (cartesian)

### Let us explore the snappyHexMeshDict dictionary.



#### **Castellated mesh controls section**



This point defines where do you want the mesh. Can be internal mesh or external mesh.

- If the point is inside the STL it is an internal mesh.
- If the point is inside the background mesh and outside the STL it is an external mesh.

### Let us explore the snappyHexMeshDict dictionary.



#### Snap mesh controls section



#### Note 1:

The higher the value the better the body fitted mesh. The default value is 30. If you are having problems with the mesh quality (related to the snapping step), try to increase this value to 300. Have in mind that this will increase the meshing time.

#### Note 2:

Increase this value to improve the quality of the body fitted mesh.

#### Note 3:

Increase this value to improve the quality of the edge features.

• In this step, we are generating the body fitted mesh.

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### Let us explore the snappyHexMeshDict dictionary.



#### Boundary layer mesh controls section



#### Note 1:

In this section we select the patches where we want to add the layers. We can add multiple patches (if they exist).

#### Note 2:

This patch was created in the geometry section.

#### Note 3:

Specification of feature angle above which layers are collapsed automatically.

• In this step, we are generating the boundary layer mesh.

### Let us explore the snappyHexMeshDict dictionary.



#### Mesh quality controls section



#### Note 1:

Maximum non-orthogonality angle.

#### Note 2:

Maximum skewness angle.

- During the mesh generation process, the mesh quality is continuously monitored.
- The mesher snappyHexMesh will try to generate a mesh using the mesh quality parameters defined by the user.
- If a mesh motion or topology change introduces a poor quality cell or face the motion or topology change is undone to revert the mesh back to a previously valid error free state.

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### Let us explore the snappyHexMeshDict dictionary.

debugFlags	
(	// write intermediate meshes mesh
	// write current mesh intersections as .obj files intersections
	// write information about explicit feature edge // refinement featureSeeds
	// write attraction as .obj files attraction
	// write information about layers layerInfo
);	
writeFlags	
(	// write volScalarField with cellLevel for // postprocessing scalarLevels
	// write cellSets, faceSets of faces in layer layerSets
);	// write volScalarField for layer coverage layerFields

#### Mesh debug and write controls sections



- At the end of the dictionary you will find the sections: debugFlags and writeFlags
- By default they are commented. If you uncomment them you will enable debug information.
- debugFlags and writeFlags will produce a lot of outputs that you can use to post process and troubleshoot the different steps of the meshing process.

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- This tutorial is located in the directory:
  - M101\_wolf
- In this case we are going to generate a body fitted mesh with boundary layer. This is an external mesh.
- Before generating the mesh take a look at the dictionaries and files that will be used.
- These are the dictionaries and files that will be used.
  - system/snappyHexMeshDict
  - system/surfaceFeatureExtractDict
  - system/meshQualityDict
  - system/blockMeshDict
  - constant/triSurface/wolfExtruded.stl
  - constant/triSurface/wolfExtruded.eMesh
- The file *wolfExtruded.eMesh* is generated after using the utility surfaceFeatureExtract, which reads the dictionary *surfaceFeatureExtractDict*.

- To generate the mesh, in the terminal window type:
  - 1. \$> foamCleanTutorials
  - 2. \$> blockMesh
  - 3. | \$> surfaceFeatureExtract
  - 4. \$> snappyHexMesh
  - 5. |\$> checkMesh -latestTime
- To visualize the mesh, in the terminal window type:
  - \$> paraFoam
- Remember to use the VCR controls in paraView/paraFoam to visualize the mesh intermediate steps.

- In the case directory you will find the time folders 1, 2, and 3, which contain the castellated mesh, snapped mesh and boundary layer mesh respectively. In this case, snappyHexMesh automatically saved the intermediate steps.
- Before running the simulation, remember to transfer the solution from the latest mesh to the directory **constant/polyMesh**, in the terminal type:

- \$> rm -rf 1
  \$> rm -rf 2
  \$> rm -rf 3
  \$> checkMesh -latestTime

- If you want to avoid the additional steps of transferring the final mesh to the directory **constant/polyMesh** by not saving the intermediate steps, you can proceed as follows:
  - \$> snappyHexMesh -overwrite
- When you proceed in this way, snappyHexMesh automatically saves the final mesh in the directory constant/polyMesh.
- Have in mind that you will not be able to visualize the intermediate steps.
- Also, you will not be able to restart the meshing process from a saved state (castellated or snapped mesh).
- Unless it is strictly necessary, from this point on we will not save the intermediate steps.



- At this point, we have a valid mesh to run a simulation.
- Have in mind that before running the simulation you will need to set the boundary and initial conditions in the directory **0**.
- The name and base type information of the boundary patches is saved in the file <code>constant/polyMesh/boundary</code>.
- Remember, the **base type** (patch type defined in the file *constant/polyMesh/boundary*) and the **primitive type** of the boundary conditions (patch type defined in the fields dictionary in the directory 0), must be compatible.
- You also need to use the same naming convention. That is, the name of the patches defined in the file *constant/polyMesh/boundary* and the name of the patches defined in the files inside the directory 0, must be the same.

### Let us generate the mesh of the wolf dynamics logo.

### The constant/polyMesh/boundary dictionary

- First at all, this file is automatically generated after you create the mesh or you convert it from a third party format.
- In this file, the geometrical information related to the **base type** patch of each boundary of the domain is specified.
- The **base type** boundary condition is the actual surface patch where we are going to apply a **primitive type** boundary condition (or numerical boundary condition).
- The **primitive type** boundary condition assign a field value to the surface patch (**base type**).
- You define the **numerical type** patch (or the value of the boundary condition), in the directory **0** or time directories.
- The name and base type of the patches was defined in the dictionaries *blockMeshDict* and *snappyHexMeshDict*.
- You can change the **name** if you do not like it. Do not use strange symbols or white spaces.
- You can also change the **base type**. For instance, you can change the type of the patch **maxY** from **wall** to **patch**.
Let us generate the mesh of the wolf dynamics logo.

					Number of surface patche	es e
18	9	-			In the list bellow there must	be 9 patches
19	(				definition	·
20		minX				
21		{				
22			type	wall;		
23			inGroups	<b>1</b> (wall);		
24			nFaces	400;		
25			startFace	466399;	mawV	woit_waii
26		}			liidX f	
27		maxX				
28		{				
29			type	wall;		
30			inGroups	<b>1</b> (wall);		
31			nFaces	400;		
32			startFace	466799;		
33		}			min7	
34		minY				
35		{				
36			type	empty;		
37			inGroups	1(wall);		
38			nFaces	400;		
39			startFace	467199;		
40		}				
41		maxY			minV N	maxX
42		{				
43		•	type	wall;		
44			inGroups	1(wall);		
45			nFaces	400		
46			startFace	467599;		
47		}				$\backslash \setminus \backslash$
48		, minZ				
49		f			A A A A A A A A A A A A A A A A A A A	Пал
50		·	tvpe	wall;		~ \
51			inGroups	1(wall):		<b>\</b>
52			nFaces	400:		\
53			startFace	467999		\
54		}				N
		,				sphere
					minY	anhana al
						sphere slave

#### Let us generate the mesh of the wolf dynamics logo.



#### Name and type of the surface patches

- The name and base type of the patch is given by the user.
- In this case the name and base type was assigned in the dictionaries *blockMeshDict* and *snappyHexMeshDict*.
- You can change the **name** if you do not like it. Do not use strange symbols or white spaces.
- You can also change the **base type**. For instance, you can change the type of the patch **maxY** from **wall** to **patch**.

#### nFaces and startFace keywords

 Unless you know what you are doing, you do not need to change this information.



- Basically, this is telling you the starting face and ending face of the patch.
- This information is created automatically when generating the mesh or converting the mesh.

#### Let us generate the mesh of the wolf dynamics logo.



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#### nFaces and startFace keywords

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- Basically, this is telling you the starting face and ending face of the patch.
- This information is created automatically when generating the mesh or converting the mesh.

### **Cleaning the case directory**

- When generating the mesh using OpenFOAM®, it is extremely important to start from a clean case directory.
- To clean all the case directory, in the terminal type:
  - \$> foamCleanTutorials
- To only erase the mesh information, in the terminal type:
  - \$> foamCleanPolyMesh
- If you are planning to start the meshing from a previous saved state, you do not need to clean the case directory.
- Before proceeding to compute the solution, remember to always check the quality of the mesh.

- Our first case will be a mesh around a cylinder.
- This is a simple geometry, but we will use it to study all the meshing steps and introduce a few advanced features.
- This case is located in the directory M1cy1



- Meshing with snappyHexMesh.
- Meshing case 1. 3D Cylinder (external mesh), with feature edge refinement.

### M1cy1/C1



- From this point on, please follow me.
- We are all going to work at the same pace.
- Remember, \$PTOFC is pointing to the path where you unpacked the tutorials.

3D Cylinder with edge refinement.





No edge refinement

Edge refinement

- If the geometry has sharp angles and you want to resolve those edges, you should use edge refinement.
- In this case and as we are interested in resolving the sharp angles, the mesh with no edge refinement is not acceptable.



- We use edge refinement when we have sharp angles.
- In the left figure there is no need to use edge refinement
- In the right figure (and depending of what you want to do), you will need to use edge refinement.

- How do we control curvature refinement and enable edge refinement?
- In the file *snappyHexMeshDict*, look for the following entry:

castellate	dMeshControls	
{		
//L	ocal curvature and	
//f	eature angle refinement	
re	solveFeatureAngle 30; To contr	ol curvature refinement
//E fe	Explicit feature edge refinement atures	
(	ſ	
	file "surfacemesh.eMesh";	To enable and control edge
		refinement level
);	,	
}		

3D Cylinder with edge refinement.

#### How resolveFeatureAngle works?



3D Cylinder with edge refinement.

#### How resolveFeatureAngle works?



- How do we control surface refinement?
- In the file *snappyHexMeshDict*, look for the following entry:



- How do we create refinement regions?
- In the file *snappyHexMeshDict*, look for the following entry:



- How do we create refinement regions?
- In the file *snappyHexMeshDict*, look for the following entry:



### 3D Cylinder with edge refinement.

#### Effect of various parameters on edge capturing and surface refinement



Surface based refinement level (2 2)

resolveFeatureAngle 60 Surface based refinement level (2 2)

- To control edges capturing you can decrease the value of **resolveFeatureAngle**.
- Be careful, this parameter also controls curvature refinement, so if you choose a low value you also will be adding a lot of refinement on the surface.

#### 3D Cylinder with edge refinement.

#### Effect of various parameters on edge capturing and surface refinement



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Explicit feature edge refinement level 0 resolveFeatureAngle 60 Surface based refinement level (2 2) Explicit feature edge refinement level 4 resolveFeatureAngle 60 Surface based refinement level (2 2)

 To control edges refinement level, you can change the value of the explicit feature edge refinement level.

#### 3D Cylinder with edge refinement.

Effect of various parameters on edge capturing and surface refinement



Explicit feature edge refinement level 6 resolveFeatureAngle 5 Surface based refinement level (2 4) Explicit feature edge refinement level 0 resolveFeatureAngle 5 Surface based refinement level (2 4)

 To control edges refinement level, you can change the value of the explicit feature edge refinement level.

### 3D Cylinder with edge refinement.

#### Effect of various parameters on edge capturing and surface refinement



Explicit feature edge refinement level 0 resolveFeatureAngle 60 Surface based refinement level (2 4) Explicit feature edge refinement level 4 resolveFeatureAngle 60 Surface based refinement level (2 2)

- To control surface refinement level, you can change the value of the surface based refinement level.
- The first digit controls the global surface refinement level and the second digit controls the curvature refinement level.

### 3D Cylinder with edge refinement.

#### Effect of various parameters on edge capturing and surface refinement



 To control surface refinement due to curvature together with control based surface refinement level, you can change the value of **resolveFeatureAngle**, and surface based refinement level

- Let us explore the dictionary *surfaceFeatureExtractDict* used by the utility *surfaceFeatureExtract*.
- This utility will extract surface features (sharp angles) according to an angle criterion (includedAngle).



- Let us explore the dictionary *surfaceFeatureExtractDict* used by the utility *surfaceFeatureExtract*.
- This utility will extract surface features (sharp angles) according to an angle criterion (includedAngle).





- If you want to have a visual representation of the feature edges, you can use paraview/paraFoam.
- Just look for the filter Feature Edges.
- Have in mind that the angle you need to define in paraview/paraFoam is the complement of the angle you define in the dictionary *surfaceFeatureExtractDict*



- In this case we are going to generate a body fitted mesh with edge refinement. This is an external mesh.
- These are the dictionaries and files that will be used.
  - system/snappyHexMeshDict
  - system/surfaceFeatureExtractDict
  - system/meshQualityDict
  - system/blockMeshDict
  - constant/triSurface/surfacemesh.stl
  - constant/triSurface/surfacemesh.eMesh
- The file *surfacemesh.eMesh* is generated after using the utility *surfaceFeatureExtract*, which reads the dictionary *surfaceFeatureExtractDict*.
- The utility surfaceFeatureExtract, will save a set of \*.obj files with the captured edges. These files are located in the directory constant/extendedFeatureEdgeMesh. You can use paraview to visualize the \*.obj files.

- Let us generate the mesh, in the terminal window type:
  - 1. \$> foamCleanTutorials
  - 2. \$> surfaceFeatureExtract

```
3. $> blockMesh
```

- 4. \$> snappyHexMesh -overwrite
- 5. \$> checkMesh -latestTime

```
6. $> paraFoam
```

- In step 2 we extract the sharp angles from the geometry.
- In step 3 we generate the background mesh.
- In step 4 we generate the body fitted mesh. Have in mind that as we use the option -overwrite, we are not saving the intermediate steps.
- In step 5 we check the mesh quality.

- Meshing with snappyHexMesh.
- Meshing case 2. 3D Cylinder (external mesh), with feature edge refinement and boundary layer.

### M1cy1/C2



- From this point on, please follow me.
- We are all going to work at the same pace.
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3D Cylinder with edge refinement and boundary layer.



### Your final mesh should looks like this one

- How do we enable boundary layer?
- In the file *snappyHexMeshDict*, look for the following entry:



- How do we enable boundary layer?
- In the file *snappyHexMeshDict*, look for the section addLayersControls:



- How do we control boundary layer collapsing?
- In the file *snappyHexMeshDict*, look for the section addLayersControls:

add {	LayersControls		
	… … // Advanced settings nGrow 0; featureAngle 130; ◀	Increa	ise this value to avoid BL sing
}	•••		

3D Cylinder with edge refinement and boundary layer.

### Effect of different parameters on the boundary layer meshing



relativeSizes true expansionRatio 1.2 finalLayerThickness 0.5 minThickness 0.1 featureAngle 130 nSurfaceLayers 3 Surface based refinement level (2 4)



relativeSizes false expansionRatio 1.2 firstLayerThickness 0.025 minThickness 0.01 featureAngle 130 nSurfaceLayers 3 Surface based refinement level (2 4)

3D Cylinder with edge refinement and boundary layer.

Effect of different parameters on the boundary layer meshing



- When the option **relativeSizes** is true, the boundary layer meshing is done relative to the size of the cells next to the surface.
- This option requires less user intervention but can not guarantee a uniform boundary layer.
- Also, it is quite difficult to set a desired thickness of the first layer.

3D Cylinder with edge refinement and boundary layer.

Effect of different parameters on the boundary layer meshing



- When the option **relativeSizes** is false, we give the actual thickness of the layers.
- This option requires a lot user intervention but it guarantees a uniform boundary layer and the desired layer thickness.

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3D Cylinder with edge refinement and boundary layer.

#### Effect of different parameters on the boundary layer meshing







relativeSizes true expansionRatio 1.2 finalLayerThickness 0.5 minThickness 0.1 featureAngle 130 nSurfaceLayers 3 Surface based refinement level (2 2)

- When the option relativeSizes is true and in order to have a uniform boundary layer, we need to have a uniform surface refinement.
- Nevertheless, we still do not have control on the desired thickness of the first layer.

3D Cylinder with edge refinement and boundary layer.

#### Effect of different parameters on the boundary layer meshing



relativeSizes true expansionRatio 1.2 finalLayerThickness 0.5 minThickness 0.1 featureAngle 130 nSurfaceLayers 3 Surface based refinement level (2 2)

•



relativeSizes true expansionRatio 1.2 finalLayerThickness 0.5 minThickness 0.1 featureAngle 30 nSurfaceLayers 3 Surface based refinement level (2 2)

To avoid boundary layer collapsing close to the corners, we can increase the value of the boundary layer parameter **featureAngle**.

3D Cylinder with edge refinement and boundary layer.

#### Effect of different parameters on the boundary layer meshing



relativeSizes false nSurfaceLayers 6



relativeSizes false nSurfaceLayers 6 Refinement region at the stl surface: mode distance; levels ((0.05 4))

- The disadvantage of setting relativeSizes to false, is that it is difficult to control the expansion ratio from the boundary layer meshing to the far mesh.
- To control this transition, we can add a refinement region at the surface with distance mode.

- To generate the mesh, in the terminal window type:
  - 1. \$> foamCleanTutorials
  - 2. \$> surfaceFeatureExtract
  - 3. \$> blockMesh
  - 4. \$> snappyHexMesh -overwrite
  - 5. \$> checkMesh -latestTime
  - 6. \$> paraFoam
3D Cylinder with edge refinement and boundary layer.

At the end of the meshing process you will get the following information regarding the boundary layer meshing:

patch	faces	layers	overall	thickness	
			[m]	[%]	
banana_stlSurface	4696	3	0.0569	95.9	┝
Layer mesh : cells:4	8577 f	aces:157942	points:61	552	

- This is a general summary of the boundary layer meshing. ٠
- Pay particular attention to the overall and thickness information. ٠
- Overall is roughly speaking the thickness of the whole boundary layer. ٠
- Thickness is the percentage of the patch that has been covered with the boundary layer mesh. A thickness of 100% means that the whole patch has been covered (a perfect BL mesh).

3D Cylinder with edge refinement and boundary layer.

If you want to visualize the boundary layer thickness, you can enable writeFlags in the *snappyhexMeshDict* dictionary,

3D Cylinder with edge refinement and boundary layer.

Then you can use paraview/paraFoam to visualize the boundary layer coverage.



Boundary layer thickness and number of layers



The yellow surface represent the BL coverage

3D Cylinder with edge refinement and boundary layer.

- After creating the mesh and if you do not like the inflation layer or you want to try different layer parameters, you do not need to start the meshing process from scratch.
- To restart the meshing process from a saved state you need to save the intermediate steps (castellation and snapping), and then create the inflation layers starting from the snapped mesh.
- That is, do not use the option snappyHeshMesh -overwrite.
- Also, in the dictionary *controlDict* remember to set the entry startFrom to latestTime or the time directory where the snapped mesh is saved (in this case 2).
- Before restarting the meshing, you will need to turn off the castellation and snapping options and turn on the boundary layer options in the *snappyHexMeshDict* dictionary.

3D Cylinder with edge refinement and boundary layer.

• Remember, before restarting the meshing you will need to modify the snappyHexMeshDict dictionary as follows:

castellatedMesh	false;
snap	false;
addLayers	true;

- At this point, you can restart the meshing process by typing in the terminal,
  - \$> snappyHexMesh
- By the way, you can restart the boundary layer mesh from a previous mesh with a boundary layer.
- So in theory, you an add one layer at a time, this will give you more control but it will require more manual work and some scripting.

#### 3D Cylinder with edge refinement and boundary layer.

- How do I know if my mesh is OK?
  - If your goal is to predict the forces at the walls, you should have a surface mesh and boundary layer mesh fine enough to resolve well the forces.
  - Also, if there is transition to turbulence you should resolve very well the boundary layer.
  - To have an idea is you are resolving well the forces, you can do a grid refinement study. Have in mind that these studies can be really expensive.





3D Cylinder with edge refinement and boundary layer.

- How do I know if my mesh is OK?
  - To avoid smearing gradients close to the walls, remember to control the transition from the boundary layer mesh to the far field mesh.





• And also you will need to have a mesh fine enough to resolve the flow features far from the body.





- Meshing with snappyHexMesh.
- Meshing case 3. 3D Cylinder (external mesh), with feature edge refinement and boundary layer, using a STL file with multiple surfaces.

#### M1cy1/C3



- From this point on, please follow me.
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3D Cylinder with edge refinement and boundary layer, using a STL file with multiple surfaces.





STL visualization with a single surface using paraview (the single surface in represented with a single color)

STL visualization with multiple surfaces using paraview (each color corresponds to a different surface)

- When you use a STL with multiple surfaces, you have more control over the meshing process.
- By default, STL files are made up of one single surface.
- If you want to create the multiple surfaces you will need to do it in the solid modeler.
- Alternatively, you can split the STL manually or using the utility surfaceAutoPatch.
- Loading multiple STLs is equivalent to using a STL with multiple surfaces.



- When you use a STL with multiple surfaces, you have more control over the meshing process.
- In this case, we were able to use different refinement parameters in the lateral and central surface patches of the cylinder.

- How do we assign different names to different surface patches?
- In the file *snappyHexMeshDict*, look for the following entry:

geometry	
{ surfacemesh.stl { type triSurfaceMesh; name stlSurface;	
regions {	
patch0	Named region in the STL file
name surface0;	User-defined patch name This is the name you need to use when sotting the boundary layer meshing
patch1 {	setting the boundary layer meshing
name surface1; }	
patch2 { name surface2;	
}	
}	
}	

- How do we refine user defined surface patches?
- In the file *snappyHexMeshDict*, look for the following entry:



- How do we control curvature refinement on surface patches?
- In the file *snappyHexMeshDict*, look for the following entry:



- How do we control curvature refinement on surface patches?
- In the file *snappyHexMeshDict*, look for the following entry:

cast {	ellatedMeshControls		
	//Local curvature and //feature angle refinement resolveFeatureAngle 60;	◄	The default value is 30. Using a higher value will capture less features.
}			

- How do we control boundary layer meshing on the surface patches? ۲
- In the file *snappyHexMeshDict*, look for the following entry:

addLayersControls {	
//Global parameters relativeSizes true; expansionRatio 1.2; finalLayerThickness 0.5; minThickness 0.1; layers	. parameters
"surface.*"	Idcards are permitted
{ nSurfaceLayers 5; } surface0 ◀ {	face patch
nSurfaceLayers 3; expansionRatio 1.0; finalLayerThickness 0.25; Constant Local BL minThickness 0.1;	parameters
}	
//Advanced settings	
}	87

- Let us first create the STL file with multiple surfaces.
- In the directory **geo**, you will find the original STL file.
- In the terminal type:

```
$> cd geo
$> surfaceAutoPatch geo.stl output.stl 130
$> cp output.stl ../constant/triSurface/surfacemesh.stl
$> cd ..
$> paraview
```

- The utility surfaceAutoPatch will read the original STL file (geo.stl), and it will find the patches using an angle criterion of 130 (similar to the angle criterion used with the utility surfaceFeatureExtract). It writes the new STL geometry in the file output.stl.
- By the way, it is better to create the STL file with multiple surfaces directly in the solid modeler.
- FYI, there is an equivalent utility for meshes, autoPatch. So if you forgot to define the patches, this utility will automatically find the patches according to an angle criterion.

## 3D Cylinder with edge refinement and boundary layer, using a STL file with multiple surfaces.

If you open the file *output.stl*, you will notice that there are three surfaces defined in the STL file. The different surfaces are defined in by the following sections:



- The name of the solid sections are automatically given by the utility surfaceAutoPatch.
- The convention is as follows: patch0, patch1, pathc2, ... patchN.
- If you do not like the names, you can change them directly in the STL file.

3D Cylinder with edge refinement and boundary layer, using a STL file with multiple surfaces.

- The new STL file is already in the **constant/triSurface** directory.
- To generate the mesh, in the terminal window type:
  - 1. \$> foamCleanTutorials
  - 2. \$> surfaceFeatureExtract
  - 3. \$> blockMesh
  - 4. \$> snappyHexMesh -overwrite
  - 5. \$> checkMesh -latestTime
- To visualize the mesh, in the terminal window type:

6. \$> paraFoam

- This case is ready to run using the solver simpleFoam. But before running, you will need to set the boundary and initial conditions.
- You will need to manually modify the file <code>constant/polyMesh/boundary</code>
- Remember:
  - **Base type** boundary conditions are defined in the file *boundary* located in the directory constant/polyMesh.
  - **Primitive** or **numerical type** boundary conditions are defined in the field variables files located in the directory **0** or the time directory from which you want to start the simulation (e.g. *U*, *p*).
  - The name of the base type boundary conditions and numerical type boundary conditions needs to be the same.
  - Also, the base type boundary condition needs to be compatible with the numerical type boundary condition.

- This case is ready to run with simpleFoam.
- If you are in a hurry and you do not want to create/edit the files 0/U, 0/p, constant/polyMesh/boundary, follow these steeps to run the case:

- 2. \$> cp system/boundary\_org constant/polyMesh/boundary
- 3. \$> renumberMesh -overwrite
- 4. \$> simpleFoam > log | tail -f log

- Meshing with snappyHexMesh.
- Meshing case 4. 2D Cylinder (external mesh).

#### M1cy1/C4



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- To generate a 2D mesh using snappyHexMesh, we need to start from a 3D. After all, snappyHexMesh is a 3D mesher.
- To generate a 2D mesh (and after generating the 3D mesh), we use the utility extrudeMesh.
- The utility extrudeMesh works by projecting a face into a mirror face. Therefore, the faces need to parallel.



- At most, the input geometry and the background mesh need to have the same width.
- If the input geometry is larger than the background mesh, it will be automatically cut by the faces of the background mesh.
- In this case, the input geometry will be cut by the two lateral patches of the background mesh.
- If you want to take advantage of symmetry in 3D, you can cut the geometry in half using one of the faces of the background mesh.

- How do we create the 2D mesh?
- After generating the 3D mesh, we use the utility extrudeMesh.
- This utility reads the *extrudeMeshDict*,



- To generate the mesh, in the terminal window type:
  - 1. \$> foamCleanTutorials
  - 2. \$> blockMesh
  - 3. \$> snappyHexMesh -overwrite
  - 4. \$> extrudeMesh
  - 5. \$> checkMesh -latestTime
  - 6. \$> paraFoam
- Remember, the utility extrudeMesh (step 4) reads the dictionary extrudeMeshDict, which is located in the directory system.

- Meshing with snappyHexMesh.
- Meshing case 5. Ahmed body (external mesh)

M3\_ahmed



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#### Ahmed body



- At this point, we all have a clear idea of how snappyHexMesh works.
- If not, please raise your hand.
- So let us go free styling and let us play around with this case.

#### Ahmed body

- In our YouTube channel you will find a playlist with many videos for this case. The playlist is titled: CFD workflow tutorial using open-source tools.
- You can find our YouTube channel in the following link: <u>https://www.youtube.com/channel/UCNNBm3KxVS1rGeCVUU1p61g</u>
- In these videos, we show a few extra features and some tips and tricks to take the most out of snappyHexMesh.
- If you get lost, read the REAME.FIRST file that you will find in the working directory.
- The dictionaries *snappyHexMeshDict* and *blockMeshDict* used in this case are very clean and ready to use. So feel free to use them as your templates.
- Our best advice is not to get lost in all the options available in the dictionary snappyHexMeshDict. Most of the times the default options will work fine.
- That being said, you only need to read in the geometries, set the feature edges and surface refinement levels, choose in which surfaces you want to add the boundary layers, and choose how many layers you want to add.
- Final advices:
  - If you are working with a complicated geometry, add one layer at a time.
  - Use paraFoam/paraview to get visual references.
  - Always check the quality of your mesh.